Scoring Indicator

Course Name: Machine Tools

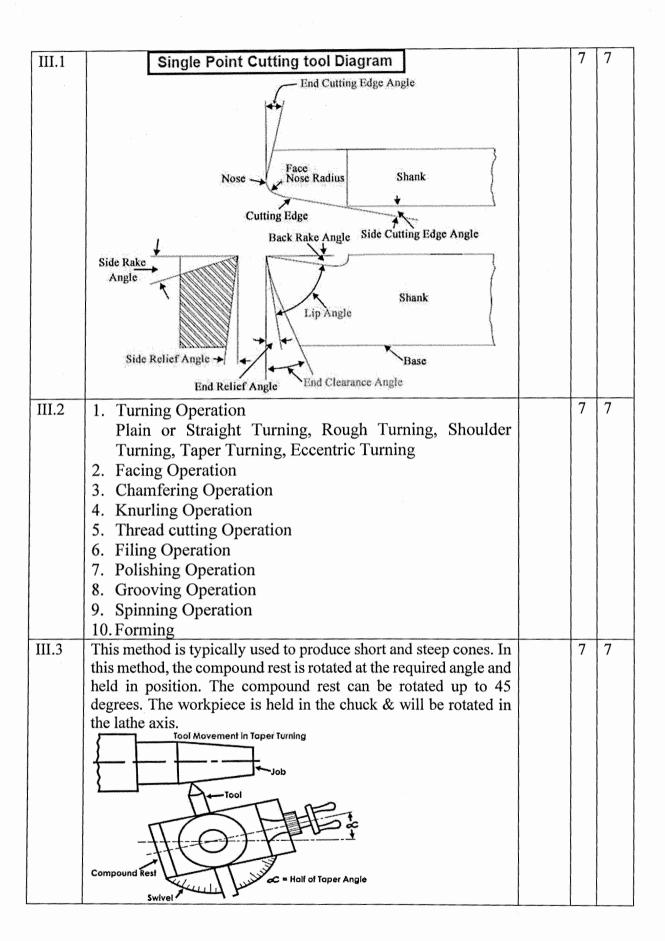
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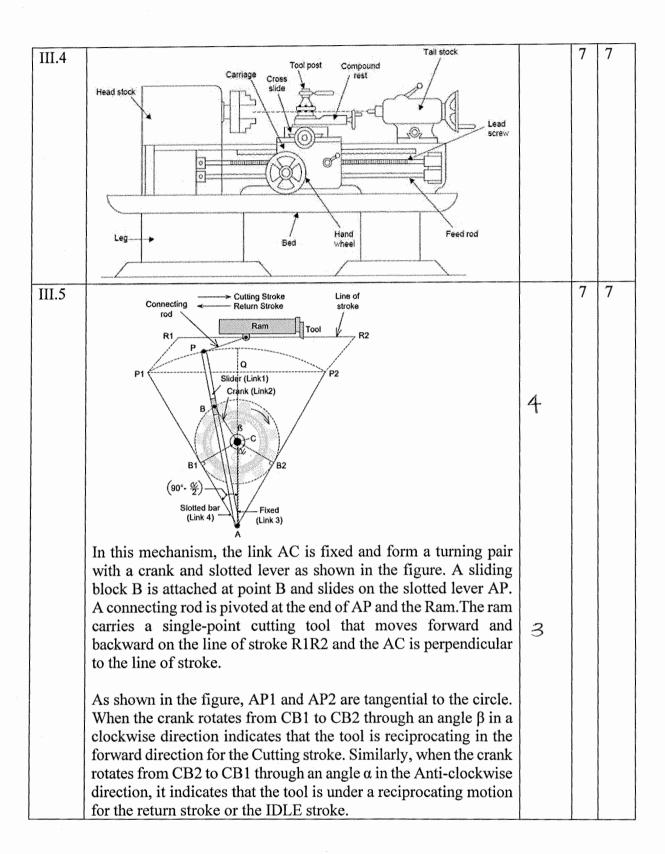
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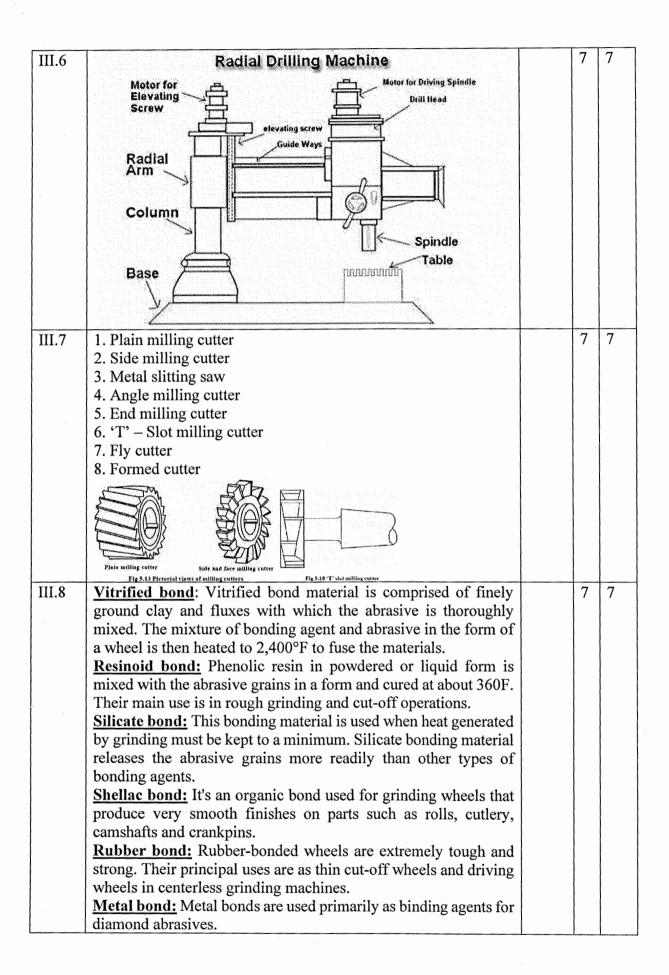
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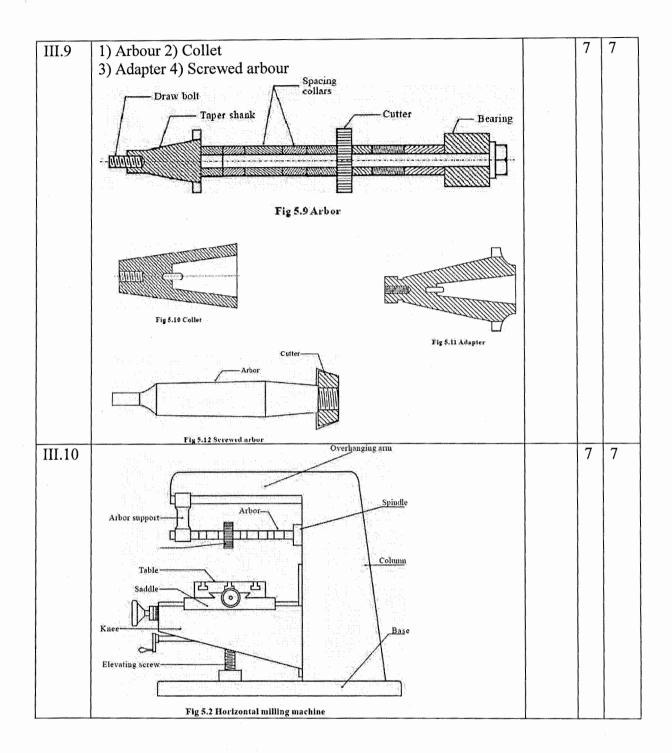
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	PART - A		1	9
I.1	Back rake angle		1	
I.2	1. Bench lathe 5. Capstan and turret lathe	Any	1	
12	2. Speed lathes 6. Automatic lathe	Two	-	
	3. Engine lathe 7. Special purpose lathes			
	4. Tool room lathe			
I.3	Heavy Duty Vices, 'T' bolts and Clamps, Step Blocks, Angle	Any	1	
	Plates, Planner Jacks, Planner Centers, 'V' blocks	One		
I.4	Reamer		1	
I.5	1. Direct or rapid indexing	Any	1	
	2. Plain or simple indexing	Two		
	3. Compound indexing			
	4. Differential indexing			
	5. Angular indexing			
I.6	(a) Sand stone or solid quartz, (b) Emery, (c) Corundum, (d)	Any	1	
	Diamonds, (e) Garnet	Two		
I.7	Program of Instructions		1_	
I.8	Industrial Manufacturing, Automotive, Industrial Robot,	Any	1	
	Aerospace, Lathing & Milling	Two		
I.9	As a Coolant, As a Lubricant, To wash off chips, to get better	Any	1	
	surfaces finish.	Two		
** 4	PART - B			24
II.1	Orthogonal Cutting:			
	Orthogonal Cutting Is a Type of Cuttings in Which the Cutting			
	Tool Is Perpendicular to the Direction of Motion. the Chip Flow			
	in This Cutting Is State-Of-The-Art. This Type of Cutting Has a		3	
	Lower Life Cutting Capacity in the Tool. Oblique Cutting:			
	Oblique cutting is a type of cuttings in which the cutting tool is			
	at an oblique angle in the direction of the tool's motion. The chip			
·	flow in this cutting is not cutting edge. The tool has a longer			
	cutting life than orthogonal cutting.			
II.2	Cutting speed, $V = 20$ m/min, Taylors exponent, $n = 1$			
	Taylors coefficient, C = 2000		3	
	Taylor's Equation, $VT^n = C$)	
	$ 20xT^1 = 2000; T = 100 $ minutes			

			1	
II.3	The work is held on a slotter table by a vise, T-bolts and clamps or by special fixtures. T-bolts and clamps are used for holding most of the work on the table. Fixtures are used for holding		3	
II.4	repetitive work. The job is rigidly fixed on the machine table. The single point cutting tool held properly in the tool post is mounted on a reciprocating ram. The reciprocating motion of the ram is obtained by a quick return motion mechanism. As the ram reciprocates, the tool cuts the material during its forward stroke. During return, there is no cutting action and this stroke is called the idle stroke. The forward and return strokes constitute one operating cycle of the shaper.		3	
II.5	 Maximum drill size (diameter) that can be used. Size and taper of the hole in the spindle. Range of spindle speeds. Range of feeds. Power of the main drive. Range of the axial travel of the spindle / bed. Floor space occupied by the machine. 	Any 3	3	
II.6	Centre less grinding is an alternative process for grinding external and internal cylindrical surfaces. In this method the workpiece is not held between centres. This results in a reduction in work handling time; hence, centre less grinding is often used for high-production work.		3	
II.7	This process uses a <u>lapping</u> plate. The abrasive particles placed between work piece and lapping plate in form of oil mixed slurry or gel. The lapping plate remains stationary in hand lapping and rotates at a speed of $10 - 150$ rpm in machine lapping. The work piece is allowed to do reciprocating motion over lapping plate which removes the material in form of microchips. It can achieve dimensional tolerance on the order of 0.0004 mm.		3	
II.8	A closed loop system uses position sensors attached to the machine tool table to measure its position relative to the input value for the axis. Any difference between the input value and the measured value is used to drive the system toward a zero difference. The function of the feedback loop in a numerical control system is to assure that the table and work part have been properly located with respect to the tool. Closed-loop NC systems generally use dc servomotors or hydraulic actuators.		3	
II.9	Numerical control technology has application in a wide variety of production operation such as metal cutting, automatic drafting, spot welding, press working, assembly, inspection, etc. However, NC finds its principal application in metal machining operations.		3	
II.10	Straight Oil, Soluble oil, mineral oil, synthetic liquids, semi- synthetic fluids, cutting oil and solid and paste lubricants		3	
	PART - C			42









III.11	There are three types of motion control used in Numerical		7	7
111.11	There are three types of motion control used in Numerical		′	'
	control			
	1. Point to point			
	2. Straight cut			
	3. Contouring			
	POINT-TO-POINT (POSITIONING) CONTROL IN NC WORKRECE			
	TOOL PATH OFENATIONS PERFORMED DURING TOOL WOTTON PARALLEL TO X OR YANIS CUTTING TOOL POINT STRAIGHT-CUT CONTROL IN NC			
	Work part Tool profile Tool path Tool path			
III.12	1. A cutting fluid should have a low viscosity so that it can easily		7	7
	flow above the workpiece.			
	2. It should have a high flash point so that it can be used at high			
	temperatures.			
	3. It should stable at high temperatures.			
	4. It should have a non-foaming tendency.	Anu		
	5. It should have a high heat absorption rate so that during cutting	Any		
	operation it can easily absorb the generated heat.	'		
	6. It should have a good lubricating property to reduce the			
	friction between tool and workpiece and chips can easily get			
	out from the workpiece.			
	7. Coolant should not react chemically; it has to be chemically			
	active in nature.			
	8. It should have odourless to avoid any bad smell even at higher			
	temperatures.			
	9. It should be transparent in a property so that the operator can			
	easily see the cutting area.			
	10. It should be harmless to the operator.			