

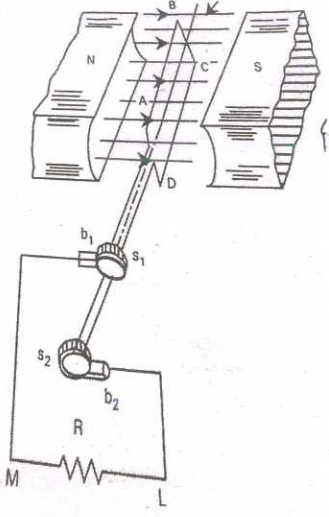
Qst. No.	Scoring Indicator	Split-up Score	Total
<u>Part-A</u>			
I			
1.	Form factor = $\frac{\text{rms value}}{\text{average value}} = 1.11$	2	
2.	<u>Instantaneous value</u> :- The strength of an alternating quantity existing in a circuit at a given instant.	2	
3.	<u>Q-factor</u> = voltage magnification in the series circuit at resonance	2	10
4.	$V_L = V_{ph}, I_L = \frac{X_L}{R} I_{ph}$	1+1	
5.	① static capacitors ② Synchronous condensers ③ Phase advancer. (any two)	2 1+1	
<u>Part-B</u>			
II			
1.	<u>Advantages of ac systems</u>		
	1. ac power generation at HV is easy 2. ac power transmission at HV is easy 3. voltage can be stepped up or down 4. ac machines are simple 5. well suited for lamps 6. wireless technology is possible 7. Any required voltage can be obtained 8. ac can be converted to dc easily (Any six)	6x1	6
2.	<u>Simple loop generator :-</u>		

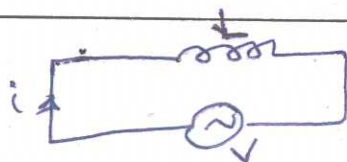
Answer Key and SCHEME OF VALUATION
(Scoring Indicators)

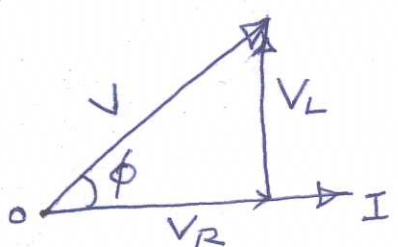
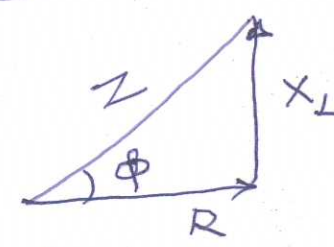
Revision:2015

Course code:3033

Course Title: Fundamentals of Ac Systems

Qst. No.	Scoring Indicator	Split-up Score	Total
		3	
	<p>* A simple coil or loop of wire is mounted on a shaft between two magnetic poles. Ends are connected to two slip rings. The brushes make proper contact with rotating slip rings and lead the current to the external load. When the rotor is rotated the flux changes and emf is induced in the stationary conductors as per Faraday's laws. The emf is alternating in nature.</p> <p>3. <u>Power consumed in a pure inductor.</u></p>	6 3	6



Qst. No.	Scoring Indicator	Split-up Score	Total
3.	<p> $v = L di/dt ; v = V_m \sin \omega t$ $\therefore L di/dt = V_m \sin \omega t ; di = \frac{V_m \sin \omega t dt}{L}$ — (1) integrating, eqn-1 $\Rightarrow i = \frac{V_m}{L} \left(-\frac{\cos \omega t}{\omega} \right)$ i.e. $i = \frac{V_m}{\omega L} \sin(\omega t - 90^\circ)$ $= I_m \sin(\omega t - 90^\circ)$ </p> <p> $I_m = \frac{V_m}{\omega L}$ when $\sin(\omega t - 90^\circ) = 1$ </p> <p> \therefore instantaneous Power = $V i$ $P = V_m \sin \omega t \times I_m \sin(\omega t - 90^\circ)$ $= -\frac{V_m I_m}{2} \sin 2\omega t$ — (2) </p> <p> Total power is obtained by integrating eqn-2 for limits 0 to 2π the integral of double frequency is zero $\therefore P = \underline{0}$ Hence showed. </p>	<p align="center">3 3 6</p>	<p align="center">6</p>
4.	<p><u>R-L series circuit.</u></p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;">  <p>(phasor diagram)</p> </div> <div style="text-align: center;">  <p>(impedance diagram)</p> </div> </div> <p>True power = $V I \cos \phi$</p> <p>Power factor, $\cos \phi = R/Z$ or $\cos \phi = \text{True Power} / \text{App. power}$</p>	<p align="center">2x1.5 1.5 1.5</p>	<p align="center">6</p>

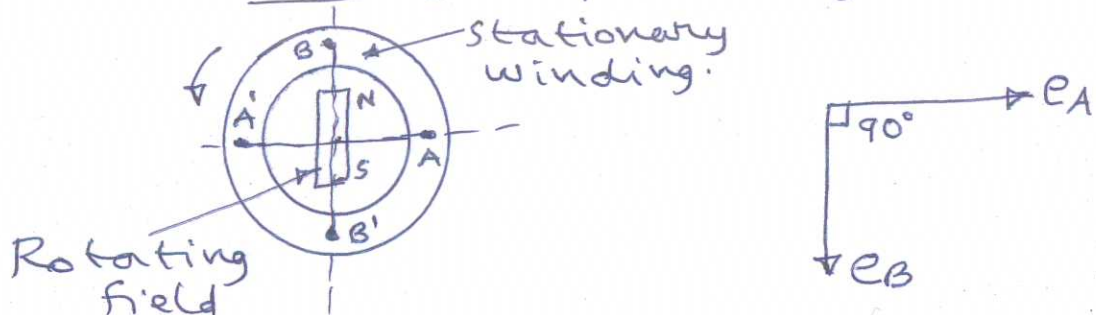
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5. Generation of 2 ϕ voltages



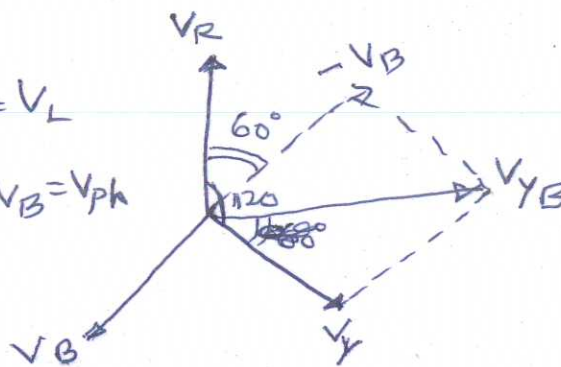
Consider two coils AA' & BB' at right angles to each other. Depending on ^{the} angular position of magnetic field, emf's induced in the coils will be maximum or zero.

$$e_A = E_m \sin \omega t ; e_B = E_m \sin (\omega t - 90^\circ)$$

6. Relation between VL and Vph in star

The line values are $V_{RY}, V_{YB}, V_{BR} = V_L$

Phase values, $V_R, V_Y, V_B = V_{ph}$



$$V_{BR} = V_B + (-V_R)$$

$$V_{RY} = V_R - V_Y = V_R + (-V_Y)$$

$$V_{YB} = V_Y + (-V_B)$$

Applying Parallelogram rule,

$$V_{YB} = V_L = \sqrt{V_Y^2 + V_B^2 + 2V_Y V_B \cos 60^\circ}$$

$$\text{i.e. } V_L = \sqrt{V_{ph}^2 + V_{ph}^2 + 2V_{ph} \cdot V_{ph} \times \frac{1}{2}}$$

$$= \sqrt{3 V_{ph}^2} = \sqrt{3} V_{ph}$$

2x1.5

3

3

3

6

6

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Course code: 3033

Course Title: Fundamentals of Ac Systems

Qst. No.	Scoring Indicator	Split-up Score	Total
7.	<p>Effect of load p.f on wattmeter readings in <u>2-wattmeter method</u></p> <p align="right"><u>R-L load</u></p> $W_1 = V_L I_L \cos(30 - \phi)$ $W_2 = V_L I_L \cos(30 + \phi)$ <p>(i) when <u>p.f = 1</u> ; $\cos \phi = 1$; $\phi = \cos^{-1} 1 = 0$</p> $W_1 = V_L I_L \cos 30 = \frac{\sqrt{3}}{2} V_L I_L$ $W_2 = V_L I_L \cos 30 = \frac{\sqrt{3}}{2} V_L I_L$ <p align="center">= half of total load power</p> <p>(ii) when <u>p.f = 0.5</u> ; $\phi = \cos^{-1} 0.5 = 60^\circ$</p> $W_1 = \frac{\sqrt{3}}{2} V_L I_L$ $W_2 = V_L I_L \cos 90^\circ = 0 //$ <p>(iii) when <u>p.f = 0</u> ; $\phi = \cos^{-1} 0 = 90^\circ$</p> $W_1 = \frac{1}{2} V_L I_L \quad \because \cos(-60) = \frac{1}{2}$ $W_2 = -\frac{1}{2} V_L I_L \quad \because \cos(120) = -\frac{1}{2}$ <p align="center">Equal but of opposite sign</p>	<p align="center">2</p> <p align="center">2</p> <p align="center">2</p>	<p align="center">6</p>
<p><u>Part - C</u> UNIT - I</p>			
III	<p>① Equation of <u>alternating voltage flux linkages</u> = $N\phi = N\phi_m \cos \theta$ [$\theta = \omega t$]</p> <p>By Faraday's laws, $e = -N \frac{d\phi}{dt}$</p> <p>i.e. $e = -N \frac{d}{dt} (\phi_m \cos \omega t)$</p> $= N\omega \phi_m \sin \omega t \quad \text{--- ①}$ <p>but $e = E_{max}$, when $\omega t = 90^\circ$</p> <p align="center">or $E_{max} = N\omega \phi_m$.</p> <p>\therefore Eqn-① $\Rightarrow e = \underline{\underline{E_m \sin \omega t}}$</p>	<p align="center">4</p> <p align="center">3</p>	<p align="center">7</p>

Qst. No.	Scoring Indicator	Split-up Score	Total
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11)	<p>(b) (a) <u>Maximum value</u> is the <u>Peak value</u> either positive or negative</p> <p>(b) <u>Average value</u> :- That steady (dc) current which transfers across any circuit the same amount of charge as is transferred by that alternating current during the same time</p> <p>(c) <u>frequency</u> :- No. of cycles per second</p> <p>(d) <u>RMS value</u> :- That steady (dc) current which when flowing through a given circuit for a given time produces the same amount of heat as produced by the alternating current when flowing through the same circuit for the same time.</p>	2 2 2 2	8
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OR

IV (a) Representations of alternating quantity.

① By equations : ① Alternating voltage

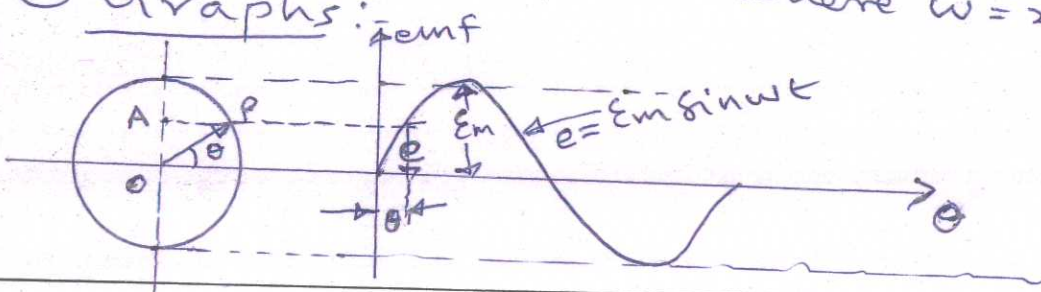
$$e = E_m \sin \omega t = E_m \sin \omega t$$

(2) current, $i = I_m \sin \omega t$

$$= I_m \sin \omega t$$

 where $\omega = 2\pi f$

By
 ② Graphs :



$$OA = OP \sin \theta \text{ or } e = OP \sin \theta = E_m \sin \theta$$

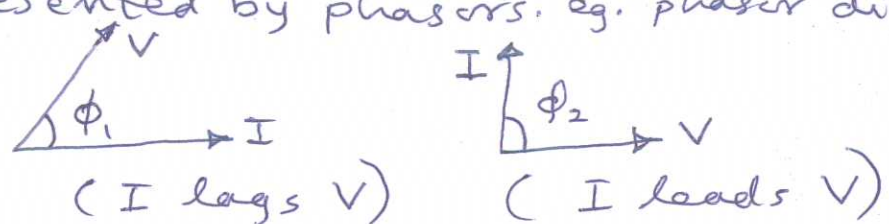
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Revision: 2015

Course Title: Fundamentals of Ac Systems

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IV (a) ③	By Phasors :- Vectors are called phasors Alternating voltage and current can be represented by phasors. eg. phasor diagrams,	2	7
	 <p>(I lags V) (I leads V)</p>		


IV (b)	$P = 30 + j52, Q = -39.5 - j14.36$ $P - Q = 30 + j52 - (-39.5 - j14.36)$ $= 69.5 + j66.36$	2	
	(a) Polar form :- slope of $P - Q = \theta = \tan^{-1}$		

$$\text{Magnitude} = \sqrt{69.5^2 + 66.36^2} = 96.093$$

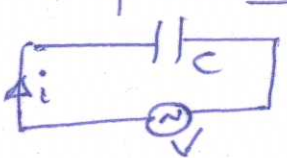
$$\theta = \tan^{-1} \left(\frac{66.36}{69.5} \right) = 43.68^\circ$$

	\therefore Polar form is $96.093 \angle 43.68^\circ$	1	8
	(b) Exponential form is $96.093 e^{j43.68}$	1	
	(c) Trigonometric form is $96.093 (\cos 43.68 + j \sin 43.68)$	1	

UNIT-II

V (a)	Power through a Pure resistance	4	
	 <p>$v = V_m \sin \omega t, i = I_m \sin \omega t$</p> $P = vi = V_m \sin \omega t \cdot I_m \sin \omega t = V_m I_m \sin^2 \omega t$ $= V_m I_m \left(\frac{1 - \cos 2\omega t}{2} \right) = \frac{V_m I_m}{2} - \frac{V_m I_m \cos 2\omega t}{2}$		

total Power is obtained by integrating eqn-1 with limit 0 to 2π

Qst. No.	Scoring Indicator	Split-up Score	Total
V(a)	But the integral of second term (double freq.) with 0 to 2π limit is zero. $\therefore P = \frac{V_m I_m}{2} = \frac{V_m}{\sqrt{2}} \times \frac{I_m}{\sqrt{2}} = V_{rms} I_{rms}$	3	7
V	(b) $R = 6\Omega, L = 0.03H, V = 50V, f = 60Hz$ $X_L = 2\pi fL = 2\pi \times 60 \times 0.03 = 11.31\Omega$ $Z = \sqrt{R^2 + X_L^2} = \sqrt{6^2 + 11.31^2} = 12.8\Omega$ (a) $I = \frac{V}{Z} = \frac{50}{12.8} = 3.906A$ (b) $P.f = \frac{R}{Z} = 0.468$ (c) Volt-ampere = $VI = 50 \times 3.906 = 195.3 VA$ (d) Reactive power = $VI \sin\phi$ $\phi = \cos^{-1}(0.468) = 62.09^\circ$ $\therefore VI \sin\phi = 50 \times 3.906 \times \sin 62.09 = 172.58 VAR$ (e) Power consumption = $VI \cos\phi = 91.547W$	2 2 1 2 1	
VI	(a) Power consumed in a pure capacitor  $V, q, C; v = V_m \sin \omega t$ $q = CV; v = q/C$ $V_m \sin \omega t = q/C; i = \frac{dq}{dt}$ or $i = C \frac{d}{dt} (V_m \sin \omega t) = \omega C V_m \cos \omega t$ $i = I_m \sin(\omega t + 90^\circ)$ Power = $v i = V_m \sin \omega t \times I_m \cos \omega t$ $= \frac{1}{2} V_m I_m \sin 2\omega t$ — (1) \therefore Total power = $\int_0^{2\pi} \frac{1}{2} V_m I_m \sin 2\omega t$	2 2 2 2	8

$= 0$ since integral of double frequency component is zero

Qst. No.	Scoring Indicator	Split-up Score	Total
<u>VI</u> (b)	<u>Series Vs Parallel ^{resonant} Circuits</u>		
	Parameters	Series ckt.	Parallel ckt
①	Resonant freq.	$\frac{1}{2\pi\sqrt{LC}}$	$\frac{1}{2\pi\sqrt{\frac{L}{C} \left(\frac{R}{L}\right)^2}}$
②	impedance at resonance	minimum	Maximum
③	current at resonance	Maximum	Minimum
④	P.f at resonance	unity	unity
⑤	Effective imped.	$Z = R$ (low)	$Z = \frac{L}{CR}$ (high)
⑥	Magnifier	voltage	current
⑦	Reactive components	$X_L = X_C$	$B_L = B_C$
⑧	Q-factor	$\frac{1}{R}\sqrt{\frac{L}{C}}$	$\frac{1}{R}\sqrt{\frac{L}{C}}$
			7x1

Any seven, 7x1 = 7

UNIT - III

VII (a) Generation of 3φ voltages

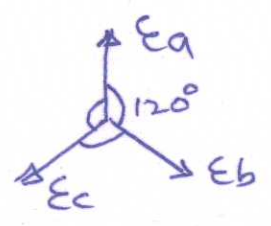
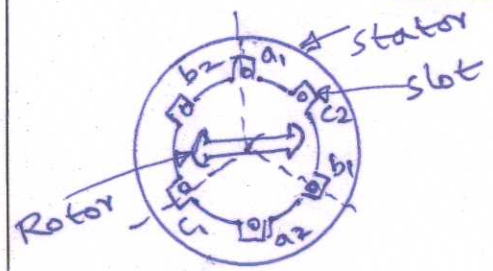


fig. → 3

emfs induced in the respective coils as the rotor rotates. The phase sequence is a-b-c. emf is zero in one coil but positive or negative in the other coils at an instant.

$$\left. \begin{aligned} e_{a1} &= E_m \sin \omega t; & e_{b1} &= E_m \sin(\omega t - 120^\circ) \\ e_{c1} &= E_m \sin(\omega t - 240^\circ) \end{aligned} \right\} \pm$$

3

7

Answer Key and SCHEME OF VALUATION
(Scoring Indicators)

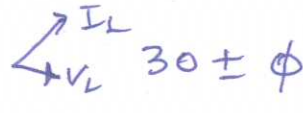
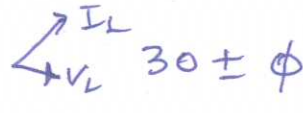
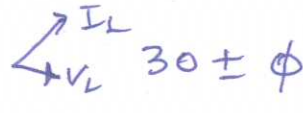
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<u>VII</u>	<p>(b) 1 star connected $R_{ph} = 8\Omega$ $X_{ph} = 6\Omega$, $V_L = 230V$ $V_{ph} = 230/\sqrt{3}$; $Z_{ph} = \sqrt{8^2 + 6^2} = 10\Omega$ $I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{230}{\sqrt{3} \times 10} = 13.28A$</p> <p>(a) $I_L = I_{ph} = 13.28A$ (c) power factor, $\cos\phi = \frac{R_{ph}}{Z_{ph}} = \frac{8}{10} = 0.8$ (lag) (b) active power = $\sqrt{3} V_L I_L \cos\phi$ $= \sqrt{3} \times 230 \times 13.28 \times 0.8$ $= 4232W$ (d) apparent power = $\sqrt{3} V_L I_L$ $= \sqrt{3} \times 230 \times 13.28$ $= 5290.4VA$</p> <p align="center">OR</p>	<p>1 1 1 2 1.5 1.5</p>	<p>8</p>
<u>VIII</u>	<p>(a) Advantages of Polyphase system</p> <ol style="list-style-type: none"> ① Power delivered is constant ② power output is 1.5 times more than 1 ϕ output power ③ 3 ϕ motors are self-starting ④ More efficiency ⑤ More power factor ⑥ Rotating magnetic field can be set-up. ⑦ More reliable ⑧ parallel operation is simple ⑨ (Any four) - 4x1 	<p>4x1</p>	<p>4</p>

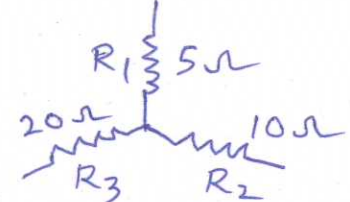

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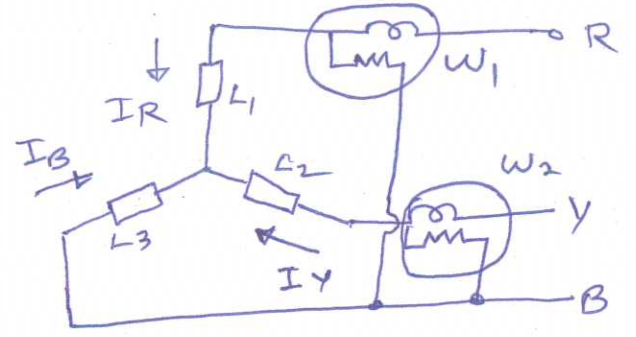
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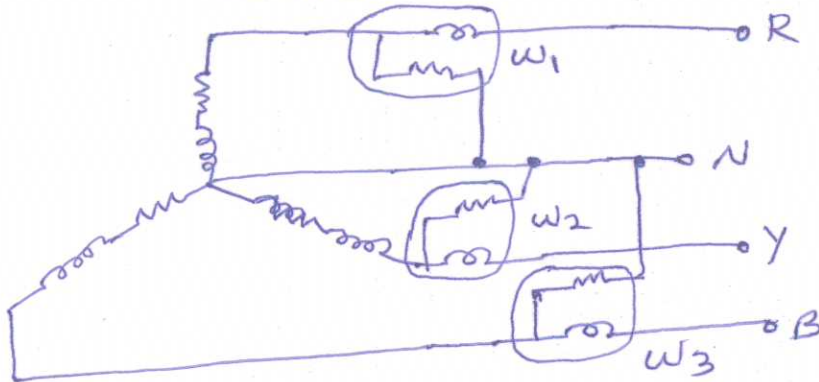
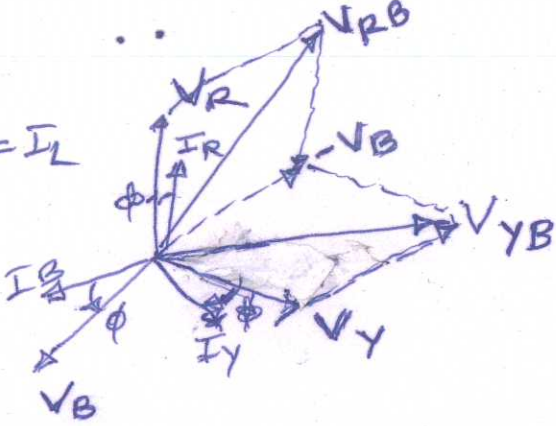
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VIII	<p>(b) <u>Comparisons of star and delta</u></p> <table style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 50%; text-align: center;"><u>Star</u></th> <th style="width: 50%; text-align: center;"><u>Delta</u></th> </tr> </thead> <tbody> <tr> <td>1. Better for 3ϕ, 4 wire distribution</td> <td>Better for 3ϕ transmission</td> </tr> <tr> <td>2. Neutral available</td> <td>Not available</td> </tr> <tr> <td>3. $I_L = I_{ph}$</td> <td>$I_L = \sqrt{3} I_{ph}$</td> </tr> <tr> <td>4. $V_L = \sqrt{3} V_{ph}$</td> <td>$V_L = V_{ph}$</td> </tr> <tr> <td>5. Power = $\sqrt{3} V_L I_L \cos \phi$</td> <td>$\sqrt{3} V_L I_L \cos \phi$</td> </tr> <tr> <td>6. </td> <td>$30^\circ \pm \phi$</td> </tr> <tr> <td>7. Line currents (or phase currents) are 120° apart</td> <td>V_L or $V_{ph} - 120^\circ$ apart</td> </tr> <tr> <td>8. I_L are 30° behind I_{ph}</td> <td>V_L are 30° ahead of V_{ph}.</td> </tr> </tbody> </table>	<u>Star</u>	<u>Delta</u>	1. Better for 3 ϕ , 4 wire distribution	Better for 3 ϕ transmission	2. Neutral available	Not available	3. $I_L = I_{ph}$	$I_L = \sqrt{3} I_{ph}$	4. $V_L = \sqrt{3} V_{ph}$	$V_L = V_{ph}$	5. Power = $\sqrt{3} V_L I_L \cos \phi$	$\sqrt{3} V_L I_L \cos \phi$	6. 	$30^\circ \pm \phi$	7. Line currents (or phase currents) are 120° apart	V_L or $V_{ph} - 120^\circ$ apart	8. I_L are 30° behind I_{ph}	V_L are 30° ahead of V_{ph} .	5x1	5
<u>Star</u>	<u>Delta</u>																				
1. Better for 3 ϕ , 4 wire distribution	Better for 3 ϕ transmission																				
2. Neutral available	Not available																				
3. $I_L = I_{ph}$	$I_L = \sqrt{3} I_{ph}$																				
4. $V_L = \sqrt{3} V_{ph}$	$V_L = V_{ph}$																				
5. Power = $\sqrt{3} V_L I_L \cos \phi$	$\sqrt{3} V_L I_L \cos \phi$																				
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8. I_L are 30° behind I_{ph}	V_L are 30° ahead of V_{ph} .																				

(Any five) 5x1

VIII	<p>(c)</p> <div style="display: flex; justify-content: space-around; align-items: center;">   </div> <p align="center">Equivalent delta values,</p> $R_{12} = R_1 + R_2 + \frac{R_1 R_2}{R_3} = 5 + 10 + \frac{5 \times 10}{20} = 17.5 \Omega \quad 2$ $R_{23} = R_2 + R_3 + \frac{R_2 R_3}{R_1} = 10 + 20 + \frac{10 \times 20}{5} = 70 \Omega \quad 2$ $R_{31} = R_1 + R_3 + \frac{R_1 R_3}{R_2} = 5 + 20 + \frac{5 \times 20}{10} = 35 \Omega \quad 2$	5x1	6
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Qst. No.	Scoring Indicator	Split-up Score	Total
IX	<p style="text-align: center;"><u>UNIT-IV</u></p> <p>(a) <u>Two wattmeter method</u></p>  <p>Let, $i_R \rightarrow$ $i_Y \rightarrow$ e_{RB}, e_{YB}</p> $W_1 = i_R (e_R - e_B), \quad W_2 = i_Y (e_Y - e_B)$ $W_1 + W_2 = i_R e_R + i_Y e_Y - e_B (i_R + i_Y) \quad \text{--- ①}$ <p>but $i_R + i_Y + i_B = 0$ $i_R + i_Y = -i_B$</p> <p>eqn-1 \rightarrow $W_1 + W_2 = i_R e_R + i_Y e_Y + i_B e_B$ $= P_R + P_Y + P_B$ $= \text{total power.}$</p> <p>(b) <u>$20 + j20 \Omega$</u> <u>delta system</u> $R_{ph} = 20 \Omega, \quad X_{ph} = 20 \Omega, \quad V_{ph} = V_L = 440V$ $Z_{ph} = \sqrt{20^2 + 20^2} = 28.284 \Omega \quad \rightarrow 1$</p> <p>(a) <u>Line current</u>, $I_{ph} = V_{ph} / Z_{ph} = \frac{440}{28.284} = 15.56 A \quad \rightarrow 1$ $\therefore I_L = \sqrt{3} I_{ph} = 26.94 A \quad \rightarrow 1$</p> <p>(b) <u>Power factor</u> $\cos \phi = \frac{R_{ph}}{Z_{ph}} = \frac{20}{28.284} = 0.707 \quad \text{--- 2 (lag)}$</p> <p>(c) $\phi = \cos^{-1}(0.707) = 45^\circ \text{ (lag)} \quad \rightarrow 1$ $\therefore W_1 = V_L I_L \cos(30 - \phi) = 11450 W \quad \rightarrow 1$ $W_2 = V_L I_L \cos(30 + \phi) = 3068 W \quad \rightarrow 1$</p>	<p style="text-align: center;">3</p> <p style="text-align: center;">4</p> <p style="text-align: center;">1</p> <p style="text-align: center;">2</p> <p style="text-align: center;">1</p> <p style="text-align: center;">1</p>	<p style="text-align: center;">7</p> <p style="text-align: center;">8</p>

Qst. No.	Scoring Indicator	Split-up Score	Total
<u>X</u>	<p align="center">OR</p> <p>(a) <u>Three wattmeter method</u></p>  <p align="center">Total power = $W_1 + W_2 + W_3$</p>	<p align="center"> Figure 3 Explanation 3 </p>	6
	<p>(b) <u>Power factor</u> in a <u>two-wattmeter method</u></p> <p>Consider a balanced star system</p>		
	<p>Let, $V_R, V_Y, V_B = V_{ph}$ $I_R, I_Y, I_B = I_{ph} = I_L$</p>  <p>I_R - current in W_1 I_Y - current in W_2</p> <p>$V_{RB} = V_R - V_B = V_R + (-V_B)$ across W_1 $V_{YB} = V_Y - V_B = V_Y + (-V_B)$ - W_2</p>		

